

Graduate Labor Economics

Discrete Choice Dynamic Programming

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Based on Keane and Wolpin (2009)

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Intro

- Dynamic Discrete Choice models have become a hallmark of empirical economics.
- Applications in Labor, IO, health, development, political economy, ...
- Aguirregabiria and Mira (2010) is an excellent survey
- Today we use Keane and Wolpin (2009) to develop a simple dynamic labor supply model.

Common Setup

- We focus on a binary choice $d_{it} \in 0, 1$. D_{it} is history of past choices.
- The latent variable v_{it} is the difference between payoffs.
- X_{it} are observed state variables, ϵ is unobserved (by us!)
- Whether v_{it} depends on entire D_{it} or just d_{it} , and how X evolves, determines whether static or dynamic model.

$$d_{it} = \begin{cases} 1 & \text{if } v_{it}(d_{it}, X_{it}, \epsilon_{it}) > 0 \\ 0 & \text{if } v_{it}(d_{it}, X_{it}, \epsilon_{it}) \leq 0 \end{cases}$$

Labor Supply of Married Women

- Consider a static model: no intertemporal dependencies.
- Utility for married woman i in period t from working (option 1) vs not working (option 0) with n_i small children is

$$U_{it}^1 = y_{it} + w_{it} - \pi n_{it} \quad (1)$$

$$U_{it}^0 = y_{it} + x_{it}\beta + \epsilon_{it} \quad (2)$$

- where y_{it} is the husband's income. Let's write the difference in those utilities as $U_{it}^1 - U_{it}^0$

Latent Value

$$v_{it}(x_{it}, w_{it}, n_{it}, \epsilon_{it}) = w_{it} - \pi n_{it} - x_{it}\beta - \epsilon_{it}$$

- define the work indicator $d_{it} = \mathbf{1}[U_{it}^1 > U_{it}^0]$
- Observed state space: $\Omega_{it} = (x_{it}, w_{it}, n_{it})$
- Unobserved by us: ϵ

Discrete Choice

- This is a threshold-crossing problem.
- Woman i will work in t if $U_{it}^1 > U_{it}^0$
- I.e. if $v_{it}(x_{it}, w_{it}, n_{it}, \epsilon_{it}) > 0$. At $v_{it}(x_{it}, w_{it}, n_{it}, \epsilon_{it}) = 0$ she is indifferent
- Call the ϵ that solves this *the critical epsilon* $\epsilon^*(\Omega_{it})$.

$$i \text{ chooses to } \begin{cases} \text{work in } t & \text{if } \epsilon_{it} < \epsilon^*(\Omega_{it}) \Rightarrow U_{it}^1 > U_{it}^0 \\ \text{not work in } t & \text{if } \epsilon_{it} > \epsilon^*(\Omega_{it}) \Rightarrow U_{it}^1 < U_{it}^0 \end{cases}$$

Setup

- Assume ϵ is independent of Ω
- then,

$$\Pr[d_{it} = 1|\Omega it] = \int_{-\infty}^{\epsilon_{it}^*} dF_{\epsilon}(\epsilon|\Omega it) = \int_{-\infty}^{\epsilon_{it}^*} dF_{\epsilon}(\epsilon)$$

- We have $\Pr[d_{it} = 0|\Omega it] = 1 - \Pr[d_{it} = 1|\Omega it]$
- Likelihood for a random sample of N females observed for T periods is

$$L(\beta, \pi, F_{\epsilon}; x_{it}, w_{it}) = \prod_{i=1}^N \prod_{t=1}^T \Pr[d_{it} = 1|\Omega it]^{d_{it}} \Pr[d_{it} = 0|\Omega it]^{1-d_{it}}$$

Notice that there are no dynamics in the model up to now!

Slightly More Realistic Wage

Potential Experience

- let's add *potential experience*
- potential experience: (age - educ - 6)

$$w_{it} = \gamma z_{it} + \eta_{it}$$

Now:

$$v_{it}(x_{it}, z_{it}, n_{it}, \epsilon_{it}, \eta_{it}) = \gamma z_{it} - \pi n_{it} - x_{it}\beta + \eta_{it} - \epsilon_{it} \quad (3)$$

$$= \tilde{\xi}_{it}^*(\Omega_{it}) + \xi_{it} \quad (4)$$

where $\tilde{\xi} = \eta - \epsilon$ is your new composite iid error, and
 $\tilde{\xi}_{it}^*(\Omega_{it}) = \gamma z_{it} - \pi n_{it} - x_{it}\beta$.

Likelihood conditional on wage

- The likelihood now is the likelihood of observing work, $d_{it} = 1$, and a certain wage w_{it} .

$$L(\beta, \pi, F_\epsilon; x_{it}, w_{it}) = \prod_{i=1}^N \prod_{t=1}^T \Pr[d_{it} = 1, w_{it} | \Omega_{it}]^{d_{it}} \quad (5) \\ \times \Pr[d_{it} = 0 | \Omega_{it}]^{1-d_{it}}$$

and we have

$$\Pr[d_{it} = 1, w_{it} | \Omega_{it}] = \Pr[d_{it} = 1, \eta_{it} = w_{it} - \gamma z_{it}]$$

Identification

- We have two latent processes:

$$w_{it} = \begin{cases} \gamma z_{it} + \eta_{it} & \text{if work} \\ 0 & \text{else} \end{cases}$$
$$d_{it} = \begin{cases} 1 & \text{if } \eta_{it} - \epsilon_{it} = \zeta_{it} > -\zeta_{it}^*(\Omega_{it}) \\ 0 & \text{else.} \end{cases}$$

- If we Assume that (ϵ, η) are joint normally distributed with

$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \Delta = \begin{pmatrix} \sigma_{\epsilon}^2 & \cdot \\ \sigma_{\epsilon\eta} & \sigma_{\eta}^2 \end{pmatrix}$$

then we get a standard **Heckman selection** model.

Identification

Identified Parameters

- 1 β_π and π are not separately identified: set $\pi = 0$.
- 2 Want to identify $\beta, \gamma, \sigma_\epsilon^2, \sigma_\eta^2, \sigma_{\epsilon\eta}$.
- 3 Let's remind ourselves of the workings of the Heckman model first.

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Setup

Suppose our latent process of interest is

$$y_{1i}^* = x_{1i}'\beta_1 + u_{1i}$$

with $E(u_1|x_1) = 0$. We observe y_1 as

$$y_{1i} = \begin{cases} y_{1i}^* & \text{if } y_{2i}^* = x_{2i}'\beta_2 + u_{2i} > 0 \\ 0 & \text{else.} \end{cases}$$

Heckman Model

- We can't run OLS on the selected sample where $y_{2i}^* > 0$:

$$\begin{aligned} E(u_{1i} | y_{2i}^* > 0) &= E(u_{1i} | x'_{2i}\beta_2 + u_{2i} > 0) \\ &= E(u_{1i} | u_{2i} > -x'_{2i}\beta_2) \\ &\neq 0 \end{aligned} \tag{6}$$

if u_1, u_2 correlated.

- But with our joint normality assumption, we can write

$$E[u_1 | u_2] = 0 + \frac{\sigma_{12}}{\sigma_2^2} u_2$$

- hence, any u_{1i} can be decomposed into a conditional mean and an error:

$$u_{1i} = \frac{\sigma_{12}}{\sigma_2^2} u_{2i} + \epsilon_{1i}, \text{ with } \epsilon_{1i} \sim \mathcal{N}(0, \sigma_\epsilon^2), \text{ independent of } u \tag{7}$$

Heckman Selection

- Substitute (7) into (6):

$$\begin{aligned} E(u_{1i}|y_{2i}^* > 0) &= E\left(\frac{\sigma_{12}}{\sigma_2^2}u_{2i} + \epsilon_{1i}|u_{2i} > -x'_{2i}\beta_2\right) \\ &= \frac{\sigma_{12}}{\sigma_2^2}E(u_{2i}|u_{2i} > -x'_{2i}\beta_2) + E(\epsilon_{1i}|u_{2i} > -x'_{2i}\beta_2) \\ &= \frac{\sigma_{12}}{\sigma_2^2}E(u_{2i}|u_{2i} > -x'_{2i}\beta_2) \end{aligned}$$

Heckman Selection

- Then use a well-known result about truncated normals:

$$\begin{aligned}\frac{\sigma_{12}}{\sigma_2^2} E(u_{2i} | u_{2i} > -x'_{2i}\beta_2) &= \frac{\sigma_{12}}{\sigma_2} \frac{\phi\left(\frac{-x'_{2i}\beta_2}{\sigma_2}\right)}{1 - \Phi\left(\frac{-x'_{2i}\beta_2}{\sigma_2}\right)} \\ &= \frac{\sigma_{12}}{\sigma_2} \frac{\phi\left(\frac{x'_{2i}\beta_2}{\sigma_2}\right)}{\Phi\left(\frac{x'_{2i}\beta_2}{\sigma_2}\right)} \\ &= \frac{\sigma_{12}}{\sigma_2} \lambda\left(\frac{x'_{2i}\beta_2}{\sigma_2}\right)\end{aligned}$$

- $\lambda(\cdot)$ is the **inverse Mills ratio**.
- So we identify $\frac{\beta_2}{\sigma_2}$. Heckman model usually imposes $\sigma_2 = 1$.

Identification Again

- Similarly here:
- Work choices identify $\frac{\beta}{\sigma_{\xi}}, \frac{\gamma}{\sigma_{\xi}}$

$$\begin{aligned}\Pr[d_{it} = 0] &= \Pr[\xi_{it} < -(z_{it}\gamma - x_{it}\beta)] \\ &= \Phi\left(-\frac{z_{it}\gamma - x_{it}\beta}{\sigma_{\xi}}\right)\end{aligned}$$

- The wage equation identifies γ and σ_{η}^2
- Identifying σ_{ξ} requires an exclusion restriction.

Exclusion Restriction

- In the likelihood function (5) there are 3 types of variables.
 - ① things only in z (i.e. wage-related)
 - ② things only in x (i.e. leisure-related)
 - ③ things in both.
- with (wage params) γ in hand, we need at least 1 element in z that is **not** in x to identify σ_{ξ}^2 and $\sigma_{\eta\epsilon}$
 - here, either education or experience should not affect leisure.

Why Assume Structure?

Part 1

- One could estimate $\Pr[d_{it} = 0]$ non-parametrically, right?
- True. **But**, separating budget set from preferences allows us to do counterfactual analysis.
- Suppose we want to know effect of implementing childcare subsidy. Couple gets $\tau > 0$ dollars if woman works.
- new budget of couple is then:

$$C_{it} = w_{it}d_{it} + y_{it} + \tau d_{it}n_{it}$$

Why Assume Structure?

Part 2

- Then resulting probability of work is

$$\begin{aligned}\Pr[d_{it} = 1 | z_{it}, x_{it}, n_{it}] &= \Pr[\xi_{it} > -(z_{it}\gamma - x_{it}\beta + \tau n_{it})] \\ &= \Phi\left(\frac{z_{it}\gamma - x_{it}\beta + \tau n_{it}}{\sigma_{\xi}}\right)\end{aligned}$$

- Without an estimate of σ_{ξ} we cannot say **anything** about the expected effect of the reform!

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Dynamic Version

- Up until now, there was no connection between **today's** choices and **tomorrow's** value.
- Even if we imposed forward-looking behaviour, this was a static optimization problem.
- Now suppose the woman's wage increases with experience h :

$$w_{it} = z_{it}\gamma_1 + h_{it}\gamma_2 + \eta_{it} \quad (8)$$

where $h_{it} = \sum_{j=1}^{j=t-1} d_{ij}$

- Clearly working today has implications for the value of tomorrow (through higher wage).

Dynamic Model Setup

- We define the remaining lifetime utility at age t as

$$V_t(\Omega_{it}) = \max_{d_{it}} \mathbb{E} \left\{ \sum_{j=t}^T \delta^{j-t} \left(U_{it}^1 d_{it} + U_{it}^0 (1 - d_{it}) \right) \mid \Omega_{it} \right\} \quad (9)$$

- with Ω as before plus h_{it} , and $h_{it} = h_{it-1} + d_{it-1}$
- We can write the value function also as

$$V_t(\Omega_{it}) = \max(V_t^0, V_t^1)$$

with

$$V_t(\Omega_{it})^j = U_{it}^j + \delta \mathbb{E} [V_{t+1}(\Omega_{it+1}) \mid \Omega_{it}, d_{it} = j], j = 0, 1$$

Dynamic Model

Latent Variable Formulation

- Similarly to before, the latent variable is

$$\begin{aligned}v_{it}(x_{it}, z_{it}, h_{it}, n_{it}, \epsilon_{it}, \eta_{it}) &= \gamma_1 z_{it} + \gamma_2 h_{it} - x_{it} \beta + \eta_{it} - \epsilon_{it} \\&\quad + \delta \mathbb{E} [V_{t+1}(\Omega_{it+1}) | \Omega_{it}, d_{it} = 1] \\&\quad - \delta \mathbb{E} [V_{t+1}(\Omega_{it+1}) | \Omega_{it}, d_{it} = 0] \\&= \zeta_{it}^*(\Omega_{it}) + \zeta_{it}\end{aligned}\tag{10}$$

- The only difference between (10) and (3) is the difference in future values.
- So, estimation would proceed as in the static case...
- ... after having computed $\mathbb{E} [\max(V_t^0(\Omega_{it}), V_t^1(\Omega_{it}))]$ at all Ω_{it} .

Estimation of the Dynamic Model

- Suppose we have a panel including h_{it} of work spells (t_{1i}, t_{Li})
- Our likelihood function becomes

$$L(\theta, x_{it}) = \prod_{i=1}^N \prod_{j=t_{1i}}^{t_{Li}} \Pr(d_{ij} = 1, w_{ij} | \Omega_{ij})^{d_{ij}} \Pr(d_{ij} = 0 | \Omega_{ij})^{1-d_{ij}} \quad (11)$$

- and as before,

$$\begin{aligned} \Pr(d_{ij} = 1, w_{ij} | \Omega_{ij}) &= \Pr(\xi_{ij} \geq -\xi_{ij}^*(\Omega_{ij}), \eta_{ij} = w_{ij} - z_{ij}\gamma_1 - \gamma_2 h_{ij}) \\ \Pr(d_{ij} = 0 | \Omega_{ij}) &= 1 - \Pr(\xi_{ij} \geq -\xi_{ij}^*(\Omega_{ij})) \end{aligned}$$

Identification of Dynamic Model

- The difference in future values in (10) is a non-linear function G :

$$v_{it}(x_{it}, z_{it}, h_{it}, n_{it}, \epsilon_{it}, \eta_{it}) = \gamma_1 z_{it} + \gamma_2 h_{it} - x_{it}\beta + \eta_{it} - \epsilon_{it} \\ + \delta G(z_{it}, h_{it}, x_{it})$$

- Functional/distributional form assumptions on G alone may be enough to identify δ .
- We require the same exclusion restriction as before for identification not based on functional form.
- Experience h should not affect leisure.

References

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